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Seventh Vector Mechanics for Engineers: Dynamics Edition 16 - 7 Axioms of the Mechanics of Rigid Bodies  
â€¢ The forces act at different points on a rigid body but but have the same magnitude, direction, and line of action.  $\sum \mathbf{r} \times \mathbf{F} = \mathbf{0}$   
â€¢ The forces produce the same moment about any point and are therefore, equipollent external forces.

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Eighth Vector Mechanics for Engineers: Statics Edition 3 - 4 Machines  $\hat{c}$  Machines are structures designed to transmit and modify forces. Their main purpose is to transform input forces into output forces.  $\hat{c}$  Given the magnitude of P, determine the magnitude of Q.  $\hat{c}$  Create a free-body diagram of the complete

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Vector Mechanics for Engineers: Statics dition 7- 22 Sample Problem 7.6  $\hat{c}$  The change in moment between A and B is equal to area under shear curve between the points. The parabolic shear curve results in a cubic moment curve.  $\hat{c}$  The change in moment between B and C is equal

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Seventh Vector Mechanics for Engineers: Dynamics Edition 12 - 4 Dynamic Equilibrium  $\hat{c}$  Alternate expression of Newton's second law,  $m\mathbf{a} = \mathbf{F}$  inertial vector  $\mathbf{F} = m\mathbf{a}$   $\hat{c}$   $\hat{c}$  With the inclusion of the inertial vector, the system of forces acting on the particle is equivalent to zero. The particle is in dynamic equilibrium.

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