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Vector components may be expressed as products of the unit vectors with the scalar magnitudes of the vector components. F_x and F_y are referred to as the scalar components of F . $F = F_x i + F_y j$
May resolve a force vector ...

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The midterm will be based on Chapters 1-5 and sections 6.1-6.7. It will be one-hour, take-home, open-text book and open-notes exam. ... resultant force vector and a resultant couple vector,

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â€¢ The forces act at different points on a rigid body but but have the same magnitude, direction, and line of action. $\mathbf{F} = F \mathbf{r}$ and $\mathbf{r} \cdot \mathbf{F} = 0$
â€¢ The forces produce the same moment about any point and are therefore, equipollent external forces.

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Eighth Vector Mechanics for Engineers: Statics Edition 6 - 7 Simple Trusses $\hat{=}$ A rigid truss will not collapse under the application of a load. $\hat{=}$ A simple truss is constructed by successively adding two members and one connection to the basic triangular truss. $\hat{=}$ In a simple truss, $m = 2n - 3$ where m is the total number of members

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Vector Mechanics for Engineers: Statics dition 7- 22 Sample Problem 7.6 The change in moment between A and B is equal to area under shear curve between the points. The parabolic shear curve results in a cubic moment curve. The change in moment between B and C is equal

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This text is available in separate volumes, Vector Mechanics for Engineers: Statics, ninth edition, and Vector Mechanics for Engineers: Dynamics, ninth edition. In a parallel text, Mechanics for Engineers: fifth edition, the use of vector algebra is limited to the addition and subtraction of vectors, and vector differentiation is omitted.

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Seventh Vector Mechanics for Engineers: Dynamics Edition 12 - 4 Dynamic Equilibrium Alternate expression of Newton's second law, $\mathbf{F} = m\mathbf{a}$ inertial vector $\mathbf{F} = m\mathbf{a}$ With the inclusion of the inertial vector, the system of forces acting on the particle is equivalent to zero. The particle is in dynamic equilibrium.

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